

Learning and Testing Submodular Functions

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Submodularity

- Discrete analog of convexity/concavity, “law of diminishing returns”
- Applications: combinatorial optimization, AGT, etc.

Let $f: 2^X \rightarrow [0, R]$:

- **Discrete derivative:**

$$\partial_x f(S) = f(S \cup \{x\}) - f(S), \quad \text{for } S \subseteq X, x \notin S$$

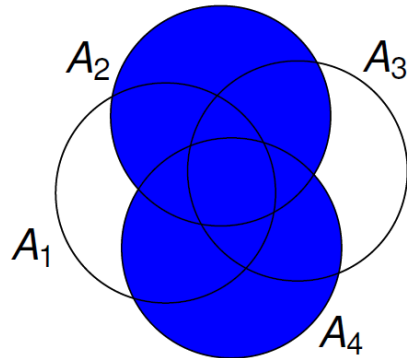
- **Submodular function:**

$$\partial_x f(S) \geq \partial_x f(T), \quad \forall S \subseteq T \subseteq X, x \notin T$$

Coverage function:

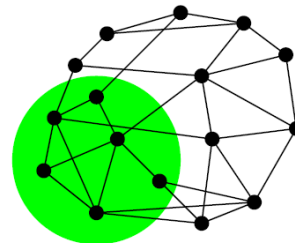
Given $A_1, \dots, A_n \subset U$,

$$f(S) = \left| \bigcup_{j \in S} A_j \right|.$$



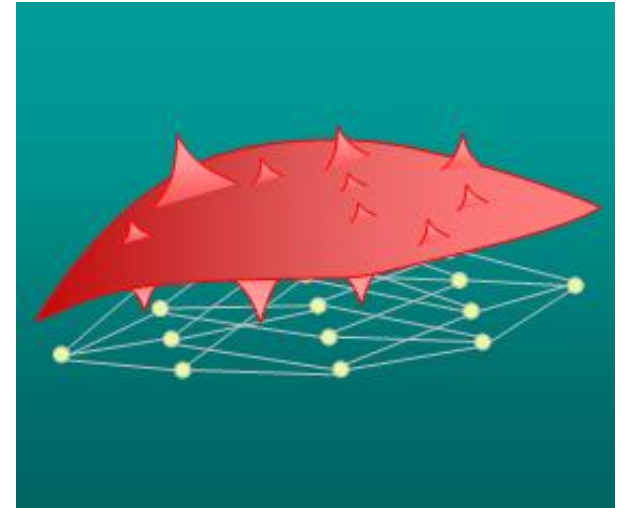
Cut function:

$$\delta(T) = |e(T, \bar{T})|$$



Approximating everywhere

- **Q1:** Approximate a submodular $f: 2^X \rightarrow [0, R]$ for all arguments with only $\text{poly}(|X|)$ queries?
- **A1:** Only $\tilde{\Theta}(\sqrt{|X|})$ -approximation (multiplicative) possible [Goemans, Harvey, Iwata, Mirrokni, SODA'09]



- **Q2:** Only for $(1 - \epsilon)$ -fraction of arguments (PAC-style learning with membership queries under uniform distribution)?

$$\Pr_{\text{randomness of } \mathbf{A}} \left[\Pr_{\mathbf{S} \sim U(2^X)} [\mathbf{A}(\mathbf{S}) = f(\mathbf{S})] \geq 1 - \epsilon \right] \geq \frac{1}{2}$$

- **A2:** Almost as hard [Balcan, Harvey, STOC'11].

Approximate learning

- **PMAC**-learning (**M**ultiplicative), with $\text{poly}(|X|)$ queries :

$$\Pr_{\text{rand. of } A} \left[\Pr_{\mathbf{S} \sim U(2^X)} [f(\mathbf{S}) \leq A(\mathbf{S}) \leq \alpha f(\mathbf{S})] \geq 1 - \epsilon \right] \geq \frac{1}{2}$$
$$\Omega(|X|^{\frac{1}{3}}) \leq \alpha \leq O\left(\sqrt{|X|}\right) \quad [\text{Balcan, Harvey '11}]$$

- **PAAC**-learning (**A**dditive)

$$\Pr_{\text{rand. of } A} \left[\Pr_{\mathbf{S} \sim U(2^X)} [|f(\mathbf{S}) - A(\mathbf{S})| \leq \beta] \geq 1 - \epsilon \right] \geq \frac{1}{2}$$

- Running time: $|X|^{O\left(\frac{R}{\beta}\right)^2 \log\left(\frac{1}{\epsilon}\right)}$ [Gupta, Hardt, Roth, Ullman, STOC'11]
- Running time: $\text{poly}\left(|X|^{\left(\frac{R}{\beta}\right)^2}, \log\frac{1}{\epsilon}\right)$ [Cheraghchi, Klivans, Kothari, Lee, SODA'12]

Learning $f: 2^X \rightarrow [0, R]$

- For all algorithms $\epsilon = \text{const.}$

	Goemans, Harvey, Iwata, Mirrokni	Balcan, Harvey	Gupta, Hardt, Roth, Ullman	Cheraghchi, Klivans, Kothari, Lee	Raskhodnikova, Y.
Learning	$\tilde{O}(\sqrt{ X })$ - approximation Everywhere	PMAC Multiplicative α $\alpha = O(\sqrt{ X })$	PAAC Additive β		PAC $f: 2^X \rightarrow \{0, \dots, R\}$ (bounded integral range $R \leq X $)
Time	$\text{Poly}(X)$	$\text{Poly}(X)$	$ X ^{O(\frac{R}{\beta})^2}$		$ X ^3 R^{O(R \cdot \log R)}$ $\text{Polylog}(X)$ $R^{O(R \cdot \log R)}$ queries
Extra features		Under arbitrary distribution	Tolerant queries	SQ- queries, Agnostic	

Learning: Bigger picture

Subadditive

UI

XOS = Fractionally subadditive

UI

Submodular

UI

Gross substitutes

UI

OXS

UI

UI

Additive
(linear)

Coverage (valuations)



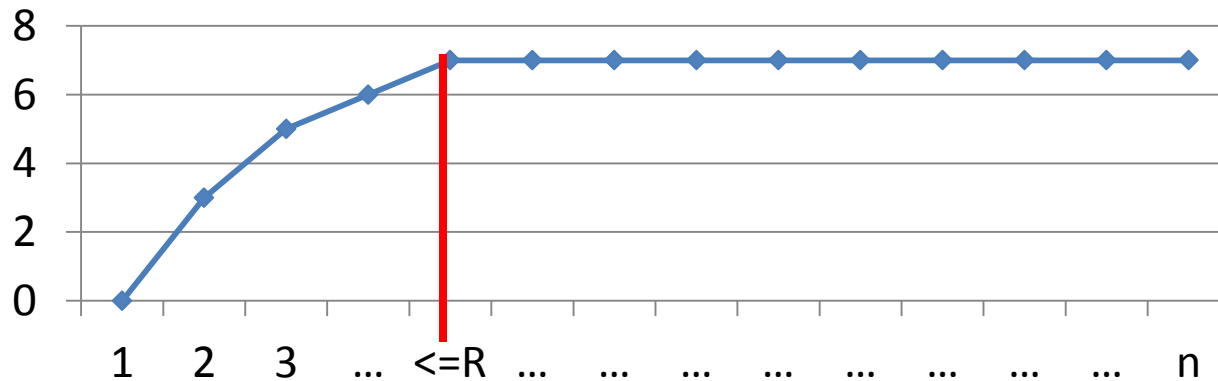
[Badanidiyuru, Dobzinski,
Fu, Kleinberg, Nisan,
Roughgarden, SODA'12]

Other positive results:

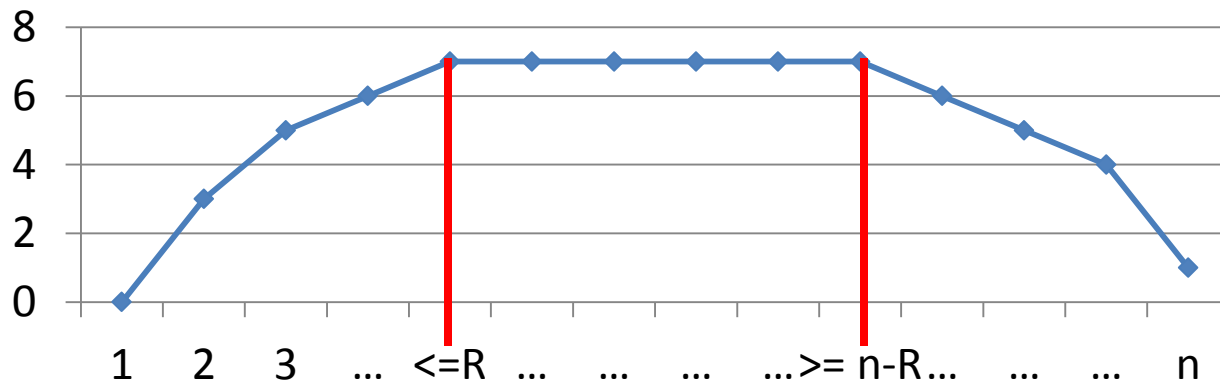
- Learning valuation functions [Balcan, Constantin, Iwata, Wang, COLT'12]
- $(1 + \epsilon)$ PMAC-learning (sketching) coverage functions [BDFKNR'12]
- $(1 + \epsilon)$ PMAC learning Lipschitz submodular functions [BH'10] (concentration around average via Talagrand)

Discrete convexity

- Monotone convex $f: \{1, \dots, n\} \rightarrow \{0, \dots, R\}$



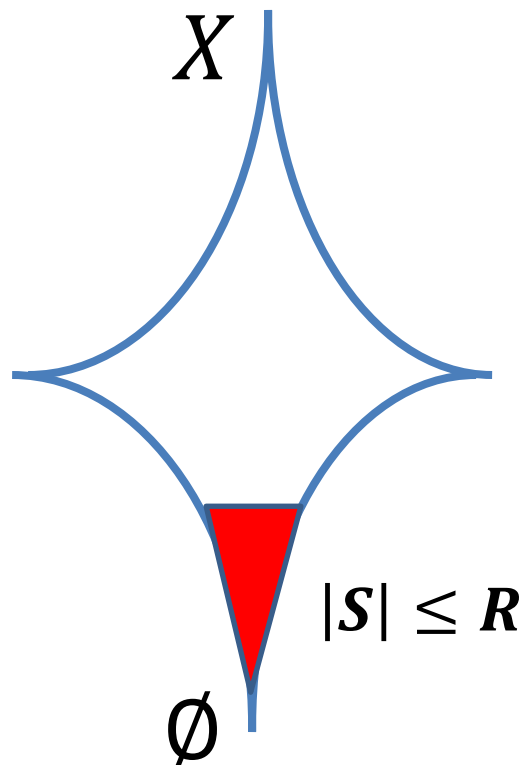
- Convex $f: \{1, \dots, n\} \rightarrow \{0, \dots, R\}$



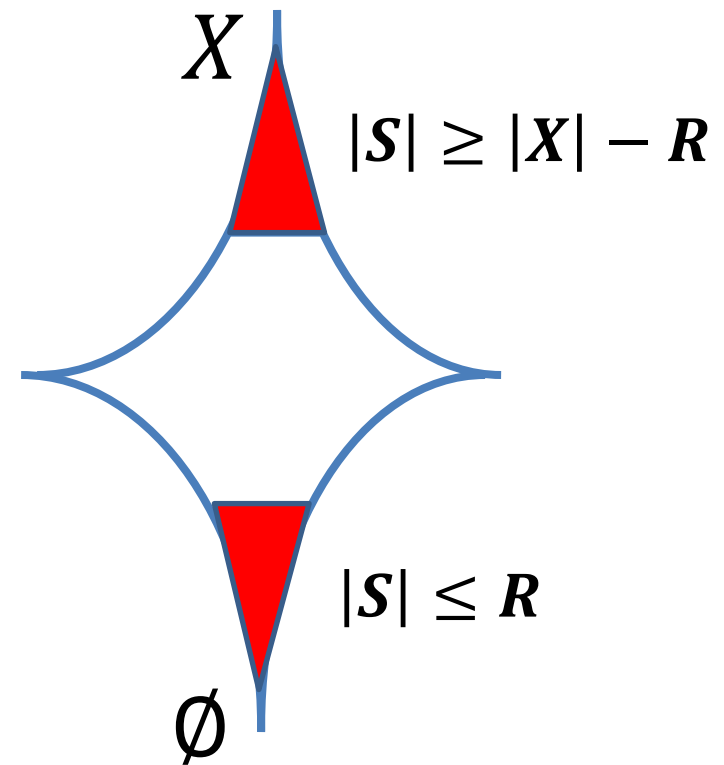
Discrete submodularity $f: 2^X \rightarrow \{0, \dots, R\}$

- **Case study:** $R = 1$ (Boolean submodular functions $f: \{0,1\}^n \rightarrow \{0,1\}$)
Monotone submodular = $x_{i_1} \vee x_{i_2} \vee \dots \vee x_{i_a}$ (monomial)
Submodular = $(x_{i_1} \vee \dots \vee x_{i_a}) \wedge (\overline{x_{j_1}} \vee \dots \vee \overline{x_{j_b}})$ (2-term CNF)

- Monotone submodular

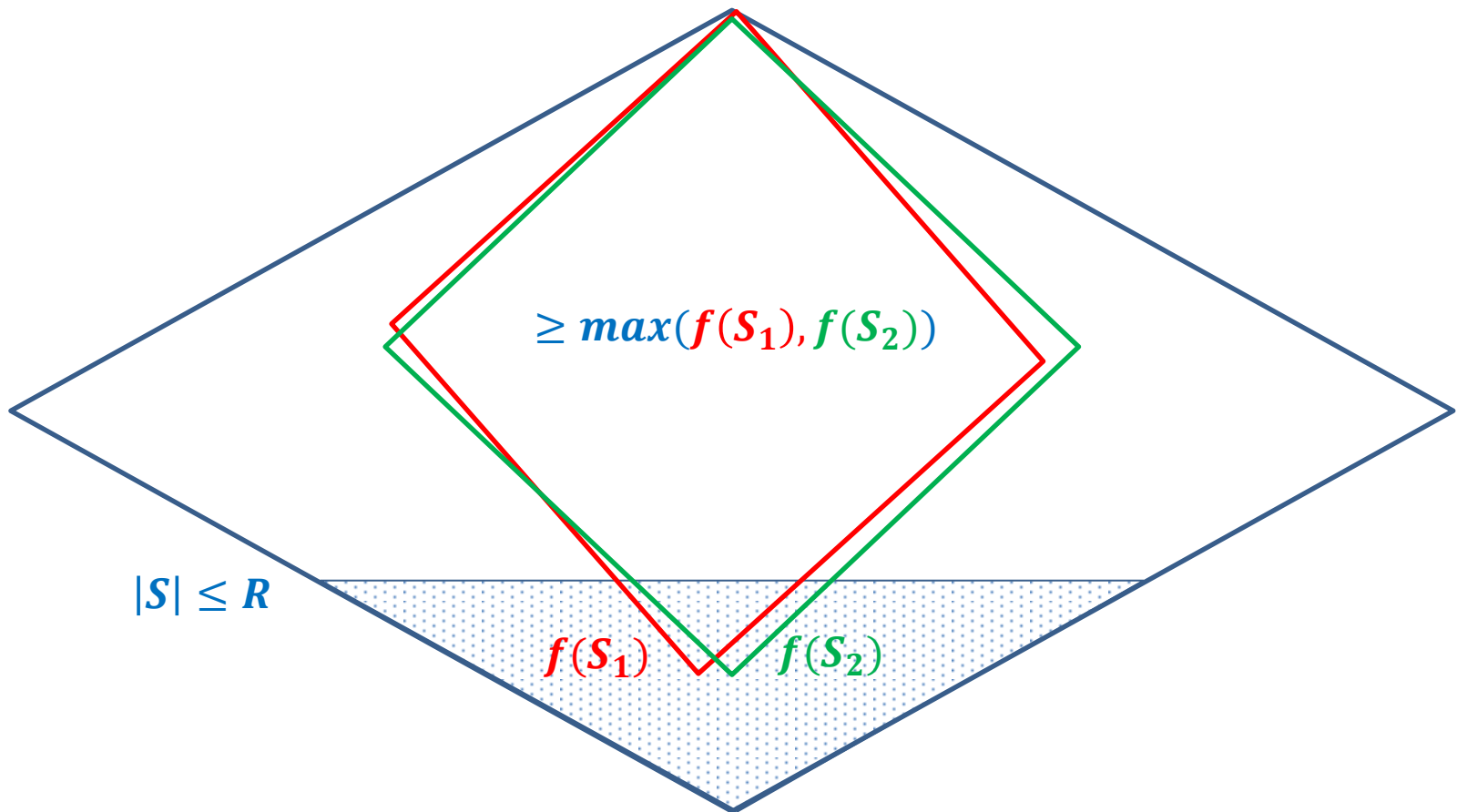


- Submodular



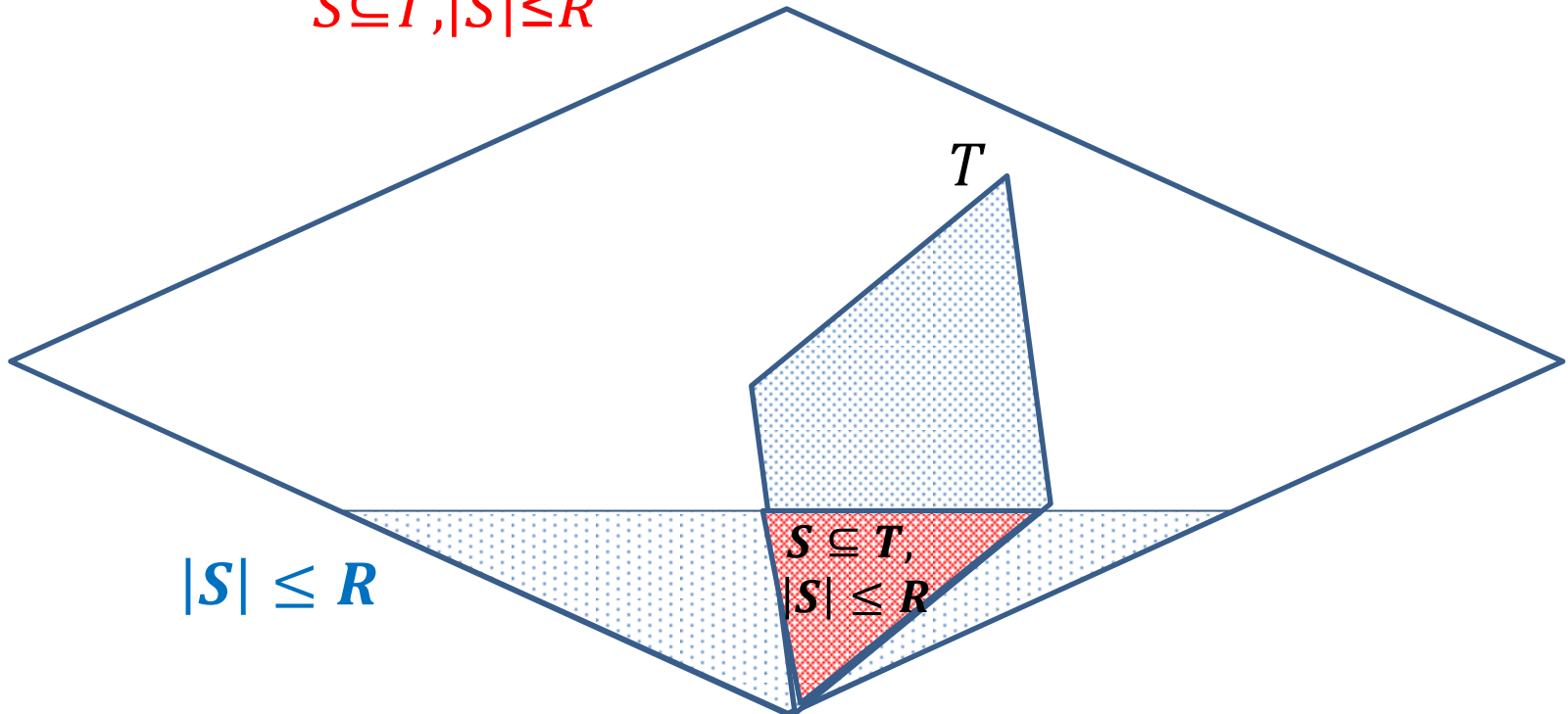
Discrete monotone submodularity

- Monotone submodular $f: 2^X \rightarrow \{0, \dots, R\}$



Discrete monotone submodularity

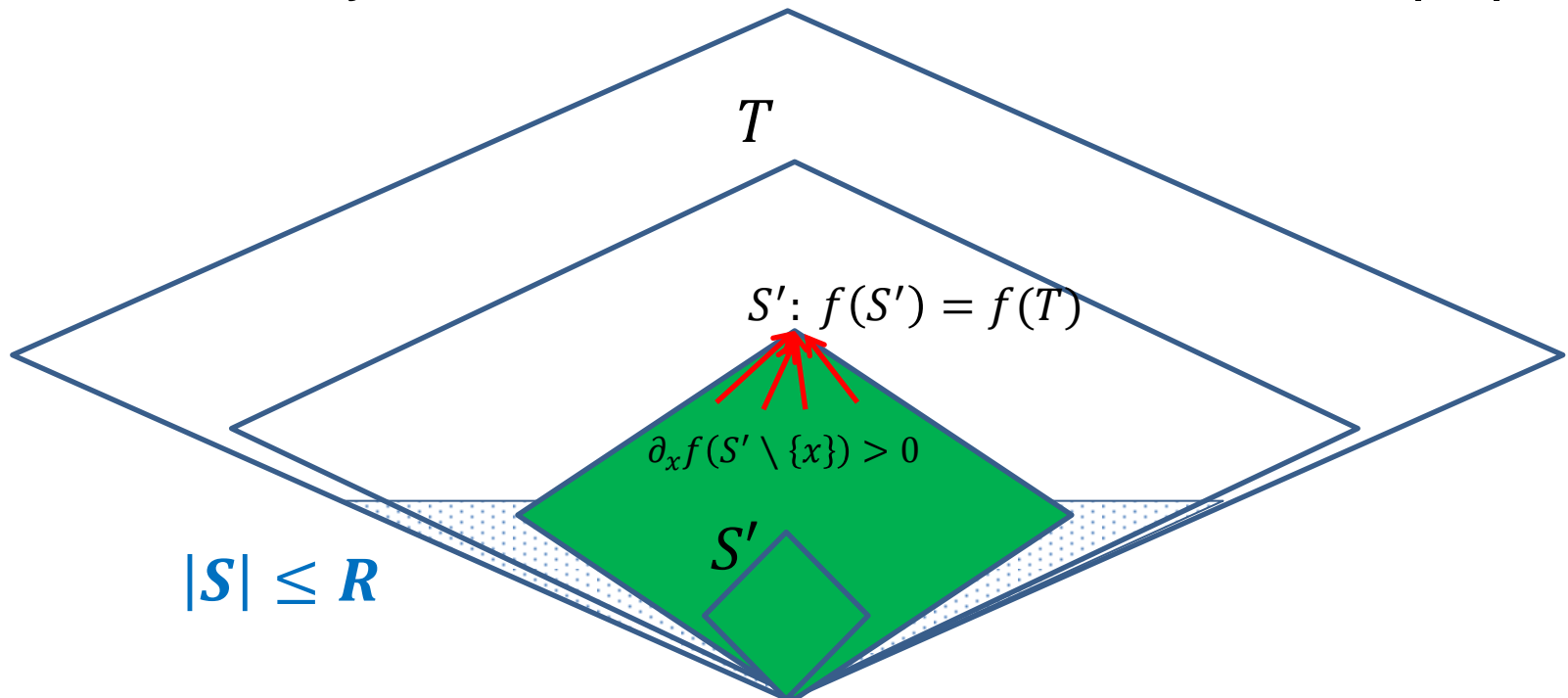
- **Theorem:** for **monotone** submodular $f: 2^X \rightarrow \{0, \dots, R\}$ for all T : $f(T) = \max_{S \subseteq T, |S| \leq R} f(S)$
- $f(T) \geq \max_{S \subseteq T, |S| \leq R} f(S)$ (by monotonicity)



Discrete monotone submodularity

- $f(T) \leq \max_{S \subseteq T, |S| \leq R} f(S)$
- $S' =$ **smallest** subset of T such that $f(T) = f(S')$
- $\forall x \in S'$ we have $\partial_x f(S' \setminus \{x\}) > 0 \Rightarrow$

Restriction of f on $2^{S'}$ is **monotone increasing** $\Rightarrow |S'| \leq R$



Representation by a formula

- **Theorem:** for **monotone** submodular $f: 2^X \rightarrow \{0, \dots, R\}$ for all T :

$$f(T) = \max_{S \subseteq T, |S| \leq R} f(S)$$

- Alternative notation: $|X| \rightarrow n, 2^X \rightarrow (x_1, \dots, x_n)$
- **Boolean k-DNF** = $\bigvee (x_{i_1} \wedge \overline{x_{i_2}} \wedge \dots \wedge x_{i_k})$
- **Pseudo-Boolean k-DNF** ($\bigvee \rightarrow \mathbf{max}, A_i = 1 \rightarrow A_i \in \mathbb{R}$):
 $\mathbf{max}_i [A_i \cdot (x_{i_1} \wedge \overline{x_{i_2}} \wedge \dots \wedge x_{i_k})]$ (**Monotone, if no negations**)
- **Theorem (restated):**
Monotone submodular $f(x_1, \dots, x_n) \rightarrow \{0, \dots, R\}$ can be represented as a **monotone** pseudo-Boolean **R**-DNF with constants $A_i \in \{0, \dots, R\}$.

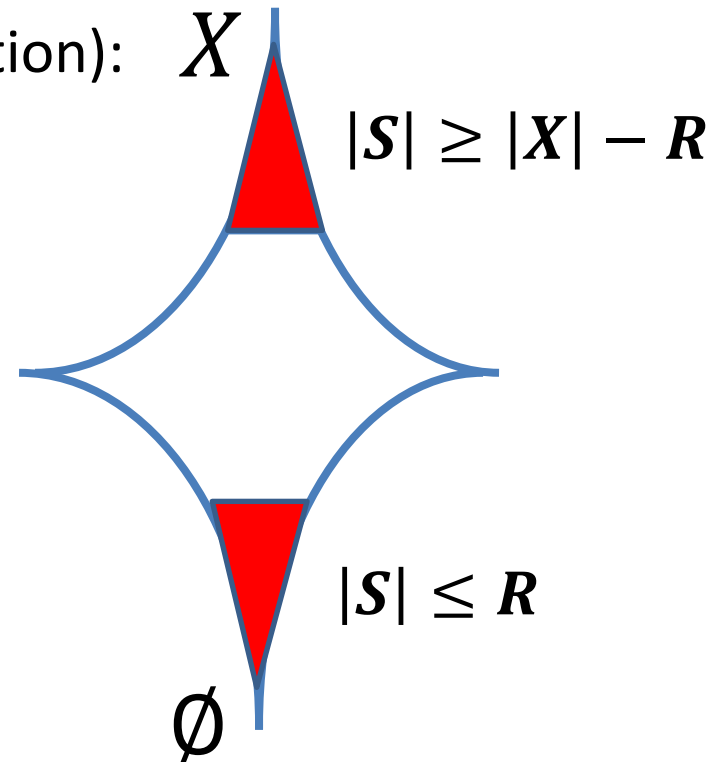
Discrete submodularity

- Submodular $f(x_1, \dots, x_n) \rightarrow \{0, \dots, R\}$ can be represented as a pseudo-Boolean $2R$ -DNF with constants $A_i \in \{0, \dots, R\}$.
- Hint [Lovasz] (Submodular monotoneization):

Given submodular f , define

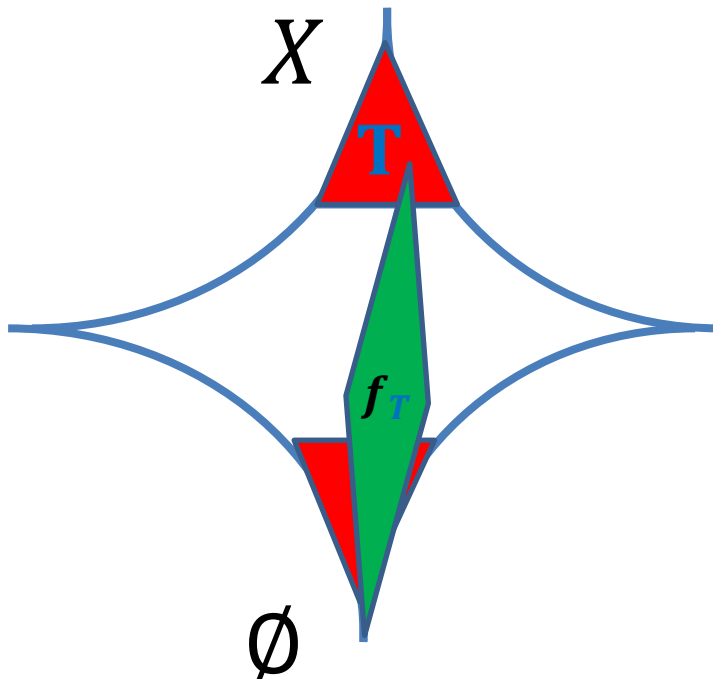
$$f^{mon}(S) = \min_{S \subseteq T} f(T)$$

Then f^{mon} is monotone and **submodular**.



Proof

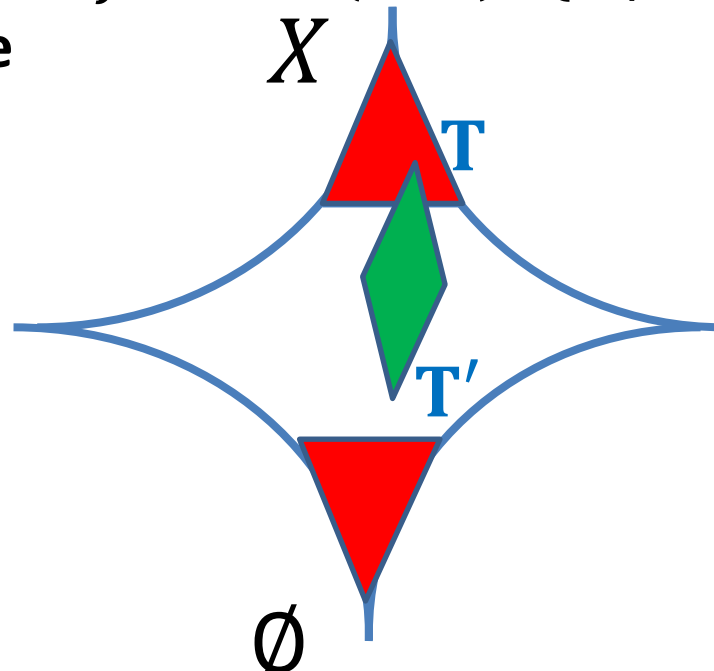
- We're done if we have a **coverage** $\mathcal{C} \subseteq 2^X$:
 1. All $T \in \mathcal{C}$ have large size: $|T| \geq |X| - R$
 2. For all $S \in 2^X$ there exists $T \in \mathcal{C} : S \subseteq T$
 3. For every $T \in \mathcal{C}$ restriction f_T of f on 2^T is **monotone**



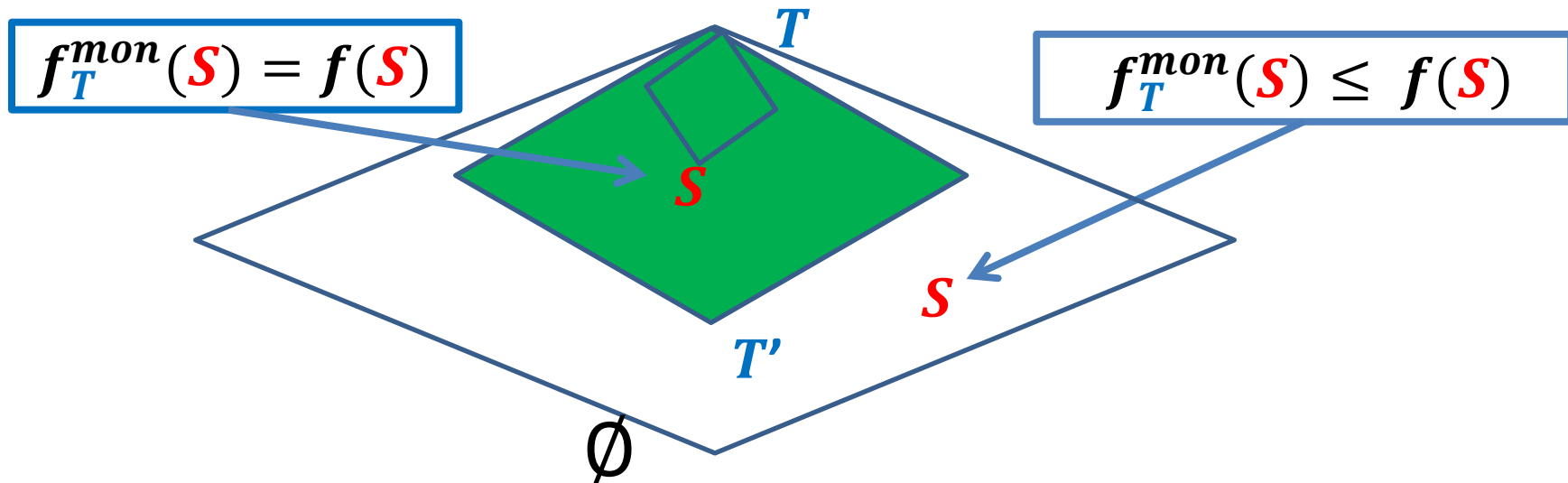
- Every f_T is a monotone pB R -DNF **(3)**
- Add at most R negated variables to every clause to restrict to 2^T **(1)**
- $f(S) = \max_{T \in \mathcal{C}} f_T(S)$ **(2)**

Proof

- There is no such coverage => relaxation [GHRU'11]
 - All $\mathbf{T} \in \mathbf{C}$ have large size: $|\mathbf{T}| \geq |\mathbf{X}| - \mathbf{R}$
 - For all $\mathbf{S} \in 2^{\mathbf{X}}$ there exists a pair $\mathbf{T}' \subseteq \mathbf{T} \in \mathbf{C}$:
$$\mathbf{T}' \subseteq \mathbf{S} \subseteq \mathbf{T}$$
 - Restriction of f on all $r(\mathbf{T}', \mathbf{T})$: $\{\mathbf{S} \mid \mathbf{T}' \subseteq \mathbf{S} \subseteq \mathbf{T}\}$ is **monotone**



Coverage by monotone lower bounds



- Let f_T^{mon} be defined as $f_T^{mon}(S) = \min_{S \subseteq S' \subseteq T} f(S')$
 - f_T^{mon} is monotone submodular [Lovasz]
 - For all $S \subseteq T$ we have $f_T^{mon}(S) \leq f(S)$
 - For all $T' \subseteq S \subseteq T$ we have $f_T^{mon}(S) = f(S)$
- $f(S) = \max_{T \in \mathcal{C}} f_T^{mon}(S)$ (where f_T^{mon} is a monotone pB R-DNF)

Learning pB-formulas and k-DNF

- $DNF^{k,R}$ = class of pB k -DNF with $A_i \in \{0, \dots, R\}$
- **i-slice** $f_i(x_1, \dots, x_n) \rightarrow \{0,1\}$ defined as

$$f_i(x_1, \dots, x_n) = 1 \quad \text{iff} \quad f(x_1, \dots, x_n) \geq i$$

- If $f \in DNF^{k,R}$ its **i-slices** f_i are k -DNF and:

$$f(x_1, \dots, x_n) = \max_{1 \leq i \leq R} (i \cdot f_i(x_1, \dots, x_n))$$

- PAC-learning:

$$\Pr_{\text{rand}(\mathbf{A})} \left[\Pr_{\mathbf{S} \sim U(\{0,1\}^n)} [\mathbf{A}(\mathbf{S}) = \mathbf{f}(\mathbf{S})] \geq 1 - \epsilon \right] \geq \frac{1}{2}$$

- Learn every **i-slice** f_i on $(1 - \epsilon / R)$ fraction of arguments \Rightarrow union bound

Learning Fourier coefficients

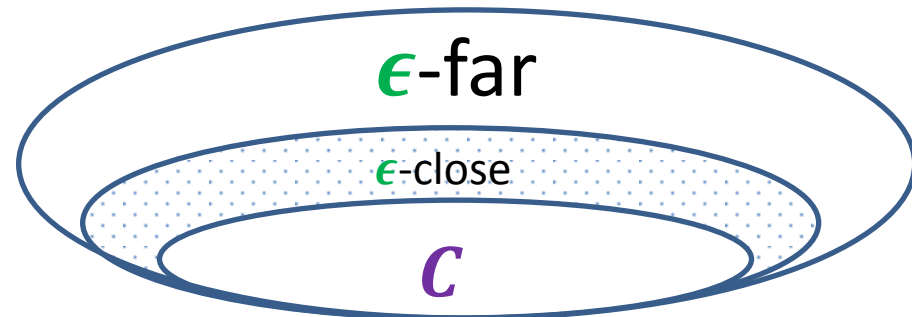
- Learn f_i (k -DNF) on $1 - \epsilon' = (1 - \epsilon / R)$ fraction of arguments
- **Fourier sparsity** $S_C(\epsilon) = \#$ of largest Fourier coefficients sufficient to PAC-learn every $f \in C$
- $S_{k\text{-DNF}}(\epsilon) = k^{O(k \log(\frac{1}{\epsilon}))}$ [Mansour]: doesn't depend on n !
 - Kushilevitz-Mansour (Goldreich-Levin): $\text{poly}(n, S_F)$ queries/time.
 - “Attribute efficient learning”: $\text{polylog}(n) \cdot \text{poly}(S_F)$ queries
 - Lower bound: $\Omega(2^k)$ queries to learn a random k -junta ($\in k$ -DNF) up to constant precision.
- $S_{DNF^{k,R}}(\epsilon) = k^{O(k \log(\frac{R}{\epsilon}))}$
 - Optimizations: Do all R iterations of KM/GL in parallel by reusing queries

Property testing

- Let \mathcal{C} be the class of submodular $f: \{0,1\}^n \rightarrow \{0, \dots, R\}$
- How to (approximately) test, whether a given f is in \mathcal{C} ?
- Property tester: (randomized) algorithm for distinguishing:

1. $f \in \mathcal{C}$

2. (ϵ -far): $\min_{g \in \mathcal{C}} |f - g|_H \geq \epsilon 2^n$



- Key idea: k -DNFs have small representations:
 - [Gopalan, Meka, Reingold CCC'12] (using quasi-sunflowers [Rossman'10])
- $\forall \epsilon > 0, \forall k$ -DNF formula F there exists:

k -DNF formula F' of size $\leq \left(k \log \frac{1}{\epsilon}\right)^{O(k)}$ such that $|F - F'|_H \leq \epsilon 2^n$

Testing by implicit learning

- **Good approximation by juntas => efficient property testing**
[Diakonikolas, Lee, Matulef, Onak, Rubinfeld, Servedio, Wan]
 - ϵ -approximation by $J(\epsilon)$ -junta
 - Good dependence on ϵ : $J_{k\text{-DNF}}(\epsilon) = \left(k \log \frac{1}{\epsilon}\right)^{O(k)}$
- For submodular functions $f: \{0,1\}^n \rightarrow \{0, \dots, R\}$
 - Query complexity $\left(R \log \frac{R}{\epsilon}\right)^{\tilde{O}(R)}$, independent of n !
 - Running time exponential in $J(\epsilon)$
 - $\Omega(k)$ lower bound for testing k -DNF (reduction from Gap Set Intersection)
- [Blais, Onak, Servedio, Y.] **exact** characterization of submodular functions

$$J(\epsilon) = \left[O \left(R \log R + \log \frac{1}{\epsilon} \right) \right]^{(R+1)}$$

Previous work on testing submodularity

$f: \{0,1\}^n \rightarrow [0, R]$ [Parnas, Ron, Rubinfeld '03, Seshadhri, Vondrak, ICS'11]:

- Upper bound $(1/\epsilon)^{O(\sqrt{n})}$.
 - Lower bound: $\Omega(n)$
- } Gap in query complexity

Special case: coverage functions [Chakrabarty, Huang, ICALP'12].

Directions

- Close gaps between upper and lower bounds, extend to more general learning/testing settings
- Connections to optimization?
- What if we use L_1 –distance between functions instead of Hamming distance in property testing?
[Berman, Raskhodnikova, Y.]